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A Scalable Remote Laboratory System for Waveform Generation Using Virtual Instrumentation

Niket Amoda^{1,a}, Lochan Jolly^{2,b} and Arpit Rawankar^{3,c}

¹*Department of Electronics & Telecommunication Engineering,
College of Engineering and Technology, Mumbai, India*

^{a)}niket.amoda@thakureducation.org
^{b)}lochan.jolly@thakureducation.org
^{c)}arpit.rawankar@thakureducation.org

Abstract. In Electronics and Telecommunication Engineering (ECE), gaining hands-on experience is just as important as understanding theory. However, traditional laboratories often come with limitations like fixed schedules, costly equipment, and restricted access. This paper introduces a practical solution a remote laboratory system built using LabVIEW and integrated with VISA and SCPI protocols that allows students to control real hardware such as Arbitrary Function Generators (AFGs) from virtually anywhere. The system supports multiple connection methods, including USB, LAN, and Wi-Fi, giving students the flexibility to access labs whether they're on campus or learning remotely. Through this setup, learners can perform real-time experiments, generate signals, and analyze live data. Performance tests show that USB delivers the fastest response, LAN offers a good balance for shared remote access, and Wi-Fi enables mobility with slightly higher latency. When compared to simulation tools and earlier remote lab setups, the proposed system offers a more realistic and interactive learning experience. By bridging the gap between theory and real-world application, it helps students build both confidence and competence in working with electronic systems.

Keywords: *Remote Lab, LabVIEW, Virtual Instrumentation, AFG3022B, Engineering Education, USB, LAN, Wi-Fi, VISA, Real-time Waveform Generation.*

INTRODUCTION

In the field of Electronics and Telecommunication Engineering (ECE), laboratory-based learning plays a vital role in reinforcing theoretical concepts through hands-on experimentation [1]. Subjects such as analog and digital communication, signal processing, embedded systems, and instrumentation require students to interact with real-world devices, observe signals, and measure performance parameters. These practical sessions are essential in bridging the gap between classroom knowledge and industry-relevant skills [2] [3].

However, traditional laboratory environments often face significant limitations. These include restricted lab hours, limited access to specialized equipment, safety concerns, and the high cost of maintaining sophisticated hardware such as signal generators, oscilloscopes, spectrum analyzers, and communication trainers [4]. Furthermore, increased student enrollment and physical space constraints make it difficult to provide every learner with sufficient hands-on exposure [5] [6].

With the growing demand for flexible and accessible education, particularly in remote and hybrid learning environments, Virtual Instrumentation based remote laboratories have emerged as a promising solution [7]. LabVIEW (Laboratory Virtual Instrument Engineering Workbench), is a graphical programming platform that enables the development of custom virtual instruments and automation systems. It supports remote access to real-time data acquisition and control, making it well-suited for virtualizing laboratory experiments [8] [2] [9].

LabVIEW's integration with VISA (Virtual Instrument Software Architecture) and SCPI (Standard Commands for Programmable Instruments) protocols allows seamless communication with a wide range of instruments, including

Arbitrary Function Generators (AFGs), Digital Storage Oscilloscopes (DSOs), and spectrum analyzers [10] [11]. By deploying LabVIEW programs on servers connected to actual lab hardware, students can remotely perform experiments such as AM/FM modulation, pulse code modulation, filter design, and frequency burst generation interacting with real signals and data from their own locations[9]. These remote laboratory systems provide several advantages:

- Real-time access to actual instruments, ensuring authentic practical learning experiences [12].
- Increased availability, allowing students to conduct experiments outside traditional class hours [10].
- Cost-effectiveness, as resources can be shared among multiple users without duplication [12].
- Safe learning environments, particularly when working with high-voltage or delicate components [10].

Numerous institutions have successfully implemented Virtual Instrumentation based remote labs for ECE education, reporting improvements in student engagement, conceptual understanding, and practical skill development [8] [2]. With continued advancements in networking and automation, remote laboratories are becoming an essential component of modern engineering education, ensuring students remain connected to hands-on learning regardless of physical location [13] [14].

While simulations are excellent tools for quickly grasping theoretical concepts and experimenting with ideas in a virtual setting, they often fall short in providing real-world, hands-on experience. In contrast, Virtual Instrumentation-based Remote Laboratories offer students the opportunity to work directly with real hardware even from remote locations making them ideal for building practical skills and gaining deeper insights into real-world systems [15] [8] [16]. A detailed comparison between simulations and remote labs is provided in Table 1 below.

TABLE 1. Comparison of Simulations with Virtual Instrumentation based Remote Laboratory [17] [18]

| Aspect | Simulations | Virtual Instrumentation based Remote Laboratories |
|-----------------------|---------------------------------------------------------------------------------|---------------------------------------------------------------------------------|
| Nature of Interaction | Virtual modeling using mathematical algorithms. | Real-time interaction with actual physical hardware. |
| Environment | Fully software-based, no real-world equipment involved. | Software interface connected to real instruments via network. |
| Data | Simulated data, not generated from real components. | Live data acquired from real devices like AFGs, DSOs, etc. |
| Conceptual Clarity | Excellent for visualizing theory. | Combines theory with hands-on practice. |
| Skill Development | Limited to software and theoretical skills. | Builds practical skills: wiring, measurement, troubleshooting. |
| Realism | Approximation of behavior. | True-to-life results from actual devices. |
| Error Handling | No real-world noise, drift, or hardware issues. | Users deal with real-world anomalies and system behaviors. |
| Limitations | No real-world interaction; cannot replicate hardware faults or real-time noise. | Needs robust infrastructure, reliable network, and remote hardware maintenance. |

PROPOSED SYSTEM

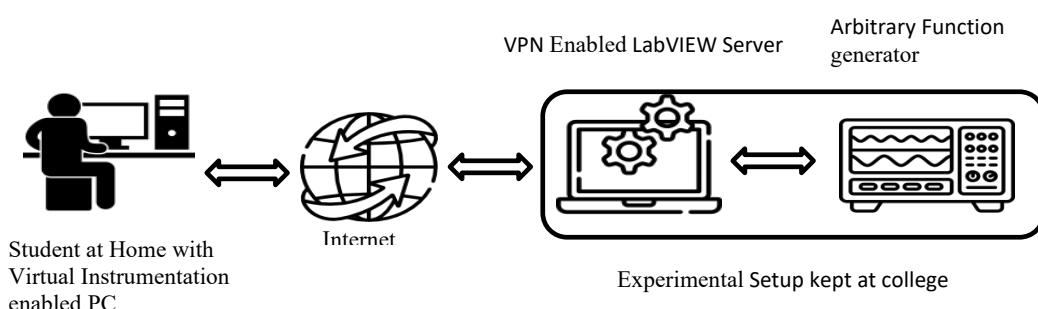


FIGURE 1. SYSTEM ARCHITECTURE

The proposed system is built around three essential components: a laptop or desktop computer at the student's home running Virtual Instrumentation software, an internet connection, and an experimental setup located in the laboratory that includes an Arbitrary Function Generator (AFG). This setup allows students particularly those studying Electronics and Telecommunication Engineering to remotely connect to and control the lab equipment from wherever they are [19] [9] [20].

Through this system, students can adjust instrument settings, monitor signals in real time, and analyze data just as they would during an in-person lab session. The experience closely mirrors being physically present in the lab, offering a practical and interactive learning environment from a distance. Figure 1 illustrates the overall architecture of the proposed system and how its components interact to support remote experimentation [21] [22].

A key enabler of this remote lab system is Virtual Instrument Software Architecture (VISA), which acts as the bridge between the student's computer and the physical lab equipment. Whether students are working with an Arbitrary Function Generator (AFG) or a Digital Storage Oscilloscope (DSO), VISA handles the behind-the-scenes communication that makes remote control possible. It provides a standardized way for Virtual Instrumentation software to talk to instruments connected through various hardware interfaces such as Ethernet, USB, GPIB, or serial ports [20][23] [24].

In the context of remote experimentation, VISA works with IP-addressed instruments (such as an AFG connected via Ethernet), allowing students to connect securely over the internet [25]. Once connected, they can adjust settings, trigger measurements, and collect data in real time just like they would if they were physically present in the lab. VISA also supports instrument discovery, session management, and error handling, which are crucial for ensuring stable and reliable connections during remote access [26] [27] [8].

SYSTEM IMPLEMENTATION

In the proposed system, a Tektronix AFG3022B Arbitrary Function Generator (AFG) was used as part of the experimental setup. To connect the AFG to a computer running LabVIEW, students have a few options USB, Ethernet (LAN), or GPIB [10]. Among these, Ethernet is the most practical and reliable choice for remote access. When using a network connection, the AFG is assigned an IP address, either automatically through DHCP or set manually. This IP address allows the Virtual Instrumentation software to identify and communicate with the device through its VISA resource name, enabling seamless remote control and integration into the LabVIEW environment [19] [18][20].

3.1 Connection of AFG to the USB



FIGURE 2 (A). USB INTERFACE OF THE AFG



FIGURE 2 (B). AFG CONNECTED TO A VIRTUAL INSTRUMENTATION ENABLED COMPUTER

Figures 2A and 2B illustrate how the Tektronix AFG3022B Arbitrary Function Generator can be connected directly to a Virtual Instrumentation enabled computer using a standard USB cable. In this setup, the device is physically linked to the computer, making it a straightforward and reliable option especially when both the user and the equipment are in the same location [28]. This type of connection doesn't require any complex network setup, which makes it ideal for local testing or development. The USB interface provides a stable and fast communication link, making it easy for students or developers to test instrument control, adjust settings, and read output signals with minimal delay.

This direct connection method is particularly helpful during the initial phases of setting up virtual instrumentation or when validating experiments before moving to a fully remote configuration [7].

3.2 Connection of AFG to the Ethernet

Figure 3A shows how the Tektronix AFG3022B Arbitrary Function Generator (AFG) can be connected to a Virtual Instrumentation-enabled computer using an Ethernet connection. In this setup, the AFG is linked to a local area network (LAN) through a standard Ethernet cable, allowing it to be accessed remotely from a computer running LabVIEW. This method is particularly useful in remote lab environments, where students or users need to control equipment from a different location [28] [10].

Once connected to the network, the AFG is assigned an IP address, either automatically via DHCP or manually through its settings as shown in Figure 3B. This IP address allows LabVIEW to recognize the instrument as a VISA resource, enabling smooth communication over the network. An Ethernet-based connection provides several advantages over direct USB connections it supports remote access, allows for multi-user setups, and offers greater scalability, especially in educational settings where multiple students may need to work with the same instrument. Overall, this configuration makes it possible to perform real-time experiments, control waveform generation, and collect data all from a remote location enhancing flexibility and accessibility in engineering education [29] [19].



FIGURE 3 (A). CONNECTION AFG TO A LOCAL AREA NETWORK (LAN) VIA ETHERNET

| | | |
|-----------------|--------------------------------------|----------|
| GPIB Address | 11 | GPIB |
| GPIB Config | Talk/Listen | |
| IP Address | 175.175.1.14 | Ethernet |
| Subnet Mask | 255.255.0.0 | |
| Default Gateway | 175.175.0.1 | |
| DHCP | On | |
| MAC Address | 08-00-11-1d-8a-32 | |
| USB ID | USB0::0x0699::0x0347::C032125::INSTR | |

FIGURE 3 (B). IP ADDRESS CONFIGURATION FOR THE AFG

3.3 Connection of AFG to the WiFi

Figure 4 illustrates the connection of the Tektronix AFG to a Virtual Instrumentation-enabled computer via a Wi-Fi network. In this setup, the AFG is first connected to a wireless router using an Ethernet cable (number 1 & 2 highlighted with yellow color), allowing the instrument to become accessible over the wireless local area network (WLAN). The student's or user's computer, equipped with LabVIEW and connected to the same Wi-Fi network, can then communicate with the AFG using the assigned IP address, similar to a standard LAN-based setup [30] [31].



FIGURE 4. CONNECTION AFG TO A WIRELESS AREA NETWORK (WAN) VIA WIFI

Although the AFG3022B itself does not support native Wi-Fi, this configuration effectively bridges the gap by allowing wireless access to the networked instrument through the router. This Wi-Fi-enabled configuration offers greater mobility and flexibility, particularly useful in academic institutes and universities where students may need to

access laboratory equipment from different locations or during off-campus sessions. However, it should be noted that compared to direct LAN or USB connections, Wi-Fi may introduce slightly higher latency and variability in performance, which should be considered for time-sensitive measurements [32] [33].

3.4 Conduction of Standard Waveform Generation Experiment

In LabVIEW, every program also known as a Virtual Instrument (VI). It has two key parts: the Front Panel and the Block Diagram. The Front Panel acts like the user interface, where users can interact with the system by entering values, adjusting controls, or viewing real-time data through graphs, charts, and indicators. It's designed to look and feel like an actual instrument panel, making it intuitive and easy to use even for those without programming experience. Behind the scenes, the Block Diagram contains the logic and flow of the program. This is where the actual data processing happens, using visual code blocks (called functions or nodes) connected by wires to represent data flow. Together, the Front Panel and Block Diagram allow users to build powerful, interactive applications that control real-world instruments, process signals, and visualize results all without writing traditional text-based code.

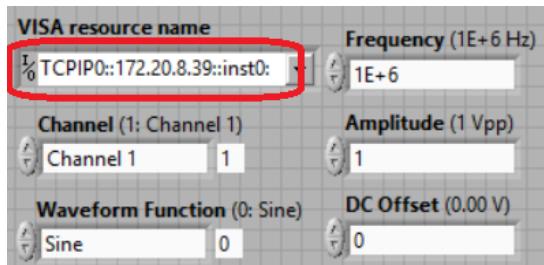


FIGURE 5(A). FRONT PANEL FOR STANDARD WAVEFORM GENERATION PROGRAM

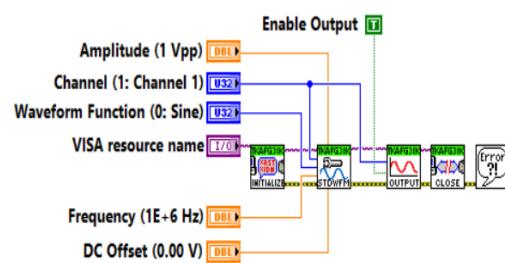


FIGURE 5(B). BLOCK DIAGRAM FOR STANDARD WAVEFORM GENERATION PROGRAM

Figures 5A and 5B illustrate the Front Panel and Block Diagram of the standard waveform generation program, which runs on the remote user's computer as part of the Virtual Instrumentation environment. This Virtual Instrumentation based program enables users to generate and control waveform signals on the Tektronix AFG3022B Arbitrary Function Generator (AFG) remotely. The connection to the instrument is established through the VISA Resource Name field, where the device's IP address is specified.

This IP address is dynamically assigned by a Virtual Private Network (VPN) enabled Virtual Instrumentation server hosted at the institute. The VPN creates a secure and reliable communication link, allowing students to operate real laboratory equipment from any off-campus location. This setup ensures that users can perform hands on experiments without being physically present in the lab replicating the experience of in person interaction with actual hardware. The Front Panel of the waveform generation program is designed to be user-friendly and includes the following key input fields:

- **VISA Resource Name:** Identifies and connects to the specific instrument over the network.
- **Channel:** Selects which output channel of the function generator is to be configured.
- **Waveform Function:** Allows the user to choose the type of waveform to generate (e.g., sine, square, triangle).
- **Frequency:** Sets the frequency of the output waveform.
- **Amplitude:** Defines the voltage amplitude of the signal generated at the output terminal
- **DC Offset:** Specifies the DC offset added to the waveform, adjusting the baseline voltage level at the output.

The results obtained from the standard waveform generation program are presented in Figures 6A to 6L, showcasing various waveform outputs and configurations achieved through remote control of the AFG device.

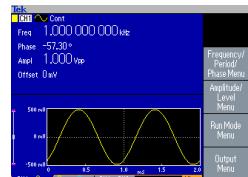


FIGURE 6(A). SINE WAVEFORM

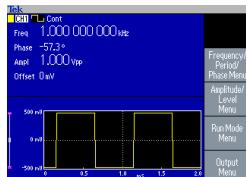


FIGURE 6(B). SQUARE WAVEFORM

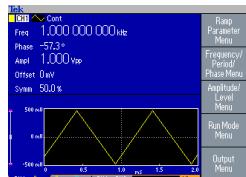


FIGURE 6(C). RAMP WAVEFORM



FIGURE 6(D). PULSE WAVEFORM

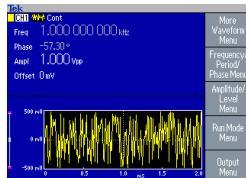


FIGURE 6(E). NOISE WAVEFORM



FIGURE 6(F). DC WAVEFORM

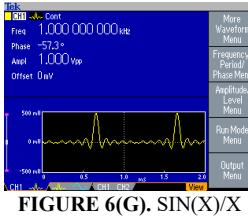


FIGURE 6(G). SIN(X)/X WAVEFORM

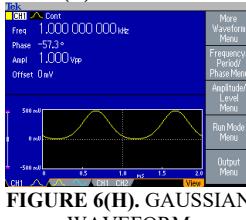


FIGURE 6(H). GAUSSIAN WAVEFORM

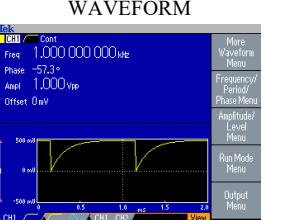


FIGURE 6(J). EXPONENTIAL RISE WAVEFORM

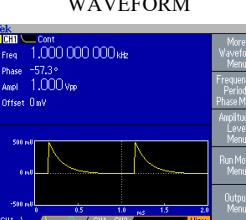


FIGURE 6(K). EXPONENTIAL DECAY WAVEFORM

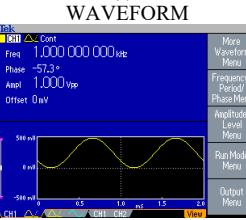


FIGURE 6(L). HAVERSINE WAVEFORM

RESULTS AND DISCUSSION

4.1 Standard Waveform generation Results

The waveform generation results obtained from remote execution are presented in Figures 6A to 6L, showcasing the system's capability to produce a wide variety of signal types:

- Figure 6A–6C: Sine, Square, and Ramp waveforms.
- Figure 6D–6F: Pulse, Noise, and DC waveforms.
- Figure 6G–6I: Sin(x)/x, Gaussian, and Lorentzian waveforms.
- Figure 6J–6L: Exponential rise, Exponential decay, and Haversine waveforms.

TABLE 2. Mean Execution time, memory and Bandwidth required to perform Standard waveform generation experiments

| Interface | Mean Execution Time in milliseconds (ms) | Mean Memory in kilobytes (KB) | Mean Bandwidth in kbps |
|-----------|------------------------------------------|-------------------------------|------------------------|
| USB | 1391.1 | 105.6 | 75.9 |
| LAN | 1429.0 | 127.6 | 89.3 |

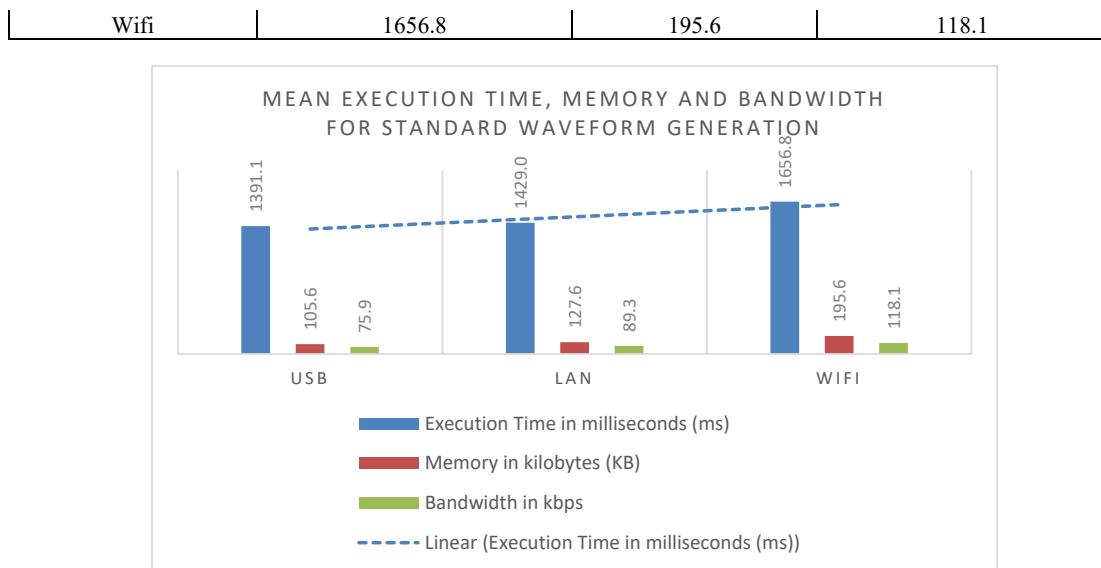


FIGURE 7. MEAN EXECUTION TIME, MEMORY AND BANDWIDTH FOR STANDARD WAVEFORM GENERATION

4.2 Performance Evaluation: Execution Time, Memory Usage, and Bandwidth

To better understand how the system performs under different types of network connections, the standard waveform generation experiment was run multiple times using USB, LAN, and Wi-Fi. The system was evaluated in terms of how long it took to complete each task (execution time), how much memory it used, and how much data it transferred (bandwidth). The results are summarized in Table 2 and displayed in Figure 7.

Among the three, the USB connection delivered the fastest and most efficient performance, with an average execution time of just 1391.1 milliseconds, the lowest memory usage at 105.6 KB, and the smallest bandwidth consumption at 75.9 kbps. This makes USB an excellent option for local testing and development, especially when students or instructors are working directly with the hardware on-site. It's simple, fast, and reliable.

The LAN (Ethernet) setup came in close behind, with a slightly higher execution time of 1429.0 milliseconds and moderate resource use. Memory consumption rose to 127.6 KB, and bandwidth to 89.3 kbps. Despite the small increase, the Ethernet connection performed consistently and was highly suitable for remote access, especially in lab environments where multiple students may need to connect to equipment simultaneously. It offers a strong balance between performance and accessibility.

The Wi-Fi configuration, while the most flexible in terms of mobility, showed the highest execution time at 1656.8 milliseconds. It also used more memory (195.6 KB) and required the most bandwidth (118.1 kbps). This is likely due to the variable nature of wireless connections, where factors like signal strength and network congestion can affect performance. Although Wi-Fi still enabled successful remote operation of the AFG, it's important to note that minor delays and occasional instability may occur—especially during time-critical tasks.

For all three connection types supported the remote waveform generation experiment effectively, but each came with its own set of trade-offs:

- USB is best for speed and simplicity when working locally.
- LAN offers a strong mix of performance and remote access.
- Wi-Fi provides the most convenience, though at the cost of slightly higher delays and resource use.

COMPARISON WITH EXISTING TECHNIQUES

To better understand where our proposed remote lab system stands, it helps to compare it with two common approaches already in use: simulation-based labs and older remote lab setups that didn't fully support real-time hardware control.

5.1 Comparison with Simulation-Based Labs

Simulation tools like MATLAB, Multisim, and Proteus are commonly used to teach electronics concepts. They're excellent for visualizing theoretical ideas and modeling circuit behavior through software. However, they don't allow students to interact with actual hardware, which means learners miss out on practical, real-world experiences. In contrast, our system provides direct control over real instruments such as the Tektronix AFG via LabVIEW, enabling students to see and respond to live data, deal with noise and fluctuations, and gain hands-on skills that simulations can't offer [34], [35], [36].

TABLE 3. Comparison of simulation-based labs and the proposed LabVIEW remote lab, focusing on interactivity, realism, and learning outcomes

| Aspect | Simulation-Based Labs | Proposed Remote Lab |
|-----------------------|----------------------------------|---------------------------------------------------------|
| Nature of Interaction | Software-based modeling | Real-time control of actual lab instruments [37] |
| Type of Data | Simulated, ideal data | Live data from physical devices [38] |
| Skill Development | Mostly theoretical | Practical skills in wiring, setup, and measurement [39] |
| Realism | Limited, lacks hardware behavior | Includes real-world issues like noise and drift [40] |
| Scalability | Easily replicable | Requires shared physical hardware [41] |
| Learning Depth | Strong in theory | Strong in both theory and hands-on practice [35], [42] |

5.2 Comparison to Older Remote Labs

Many earlier remote lab setups were more like virtual tours students could view instrument readings or video feeds, but they couldn't directly interact with the hardware in real time. The proposed system solves this problem by using LabVIEW and VISA, allowing for secure, real-time, bidirectional communication with instruments over USB, LAN, or even Wi-Fi [43], [44].

TABLE 4. Comparison of legacy remote labs with the proposed LabVIEW-based system, highlighting key improvements in control, connectivity, and user experience

| Feature | Older Remote Labs | Proposed Remote Lab |
|-----------------------|-------------------------|--------------------------------------------------|
| Real-Time Interaction | Often unavailable | Fully interactive LabVIEW control [45] |
| Protocol Support | Limited or proprietary | Uses standard VISA and SCPI protocols [46] |
| Equipment Range | Restricted | Supports a wide variety of instruments [47] |
| Network Access | Usually LAN-based | USB, LAN, and Wi-Fi support for flexibility [48] |
| Security | Basic | VPN-secured remote access [49] |
| Student Experience | Partial lab replication | Full lab experience from anywhere [35], [50] |

5.3 Key Advantages of the Proposed System

The proposed system offers several distinct benefits that make it particularly effective for modern engineering education:

- Flexible Access Options: Whether students are in the lab or halfway across campus, they can connect via USB, Ethernet, or Wi-Fi depending on what's available [48], [49].
- Real Instrumentation Training: Students gain familiarity with the same types of interfaces and equipment they'll encounter in industry [37], [39].
- Efficient and Reliable: Performance testing shows low execution times and modest bandwidth usage, especially over USB and LAN, making it viable even in bandwidth-constrained environments [51], [52].
- Scalable Design: With LabVIEW's modular programming and support for multiple users, institutions can scale this system to support a larger number of remote learners without needing duplicate hardware [43], [44].

CONCLUSION

This study presents a remote lab system that brings real instruments and experiments into students' hands no matter where they are. By combining LabVIEW with standardized communication protocols like VISA and SCPI, the setup allows students to remotely control devices like the Tektronix AFG3022B function generator and carry out practical tasks just as they would in a physical lab. Our findings show that USB connections are ideal for speed and efficiency, LAN provides reliable access for shared use, and Wi-Fi supports remote learning with minor trade-offs in speed. Together, these options make the system highly adaptable for both in-person and remote learning environments. Compared to traditional simulations and older remote labs, this approach offers a more immersive and hands-on experience. It not only improves engagement and understanding but also prepares students for working with real-world equipment an essential skill in today's engineering careers. With education increasingly moving toward hybrid and flexible models, this kind of system is not just useful it's necessary. It ensures that students can keep learning, experimenting, and building real skills, even when they can't physically be in the lab.

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